Problem 9b (2 points)

A Photovoltaic panel under a given insolation condition operates at its maximum power point with the voltage of 60 V and the current of 20 A. This PV panel supplies power to a 120-V, 60-Hz, residential grid. The PV interface consists of a boost dc-dc converter, followed by a full-bridge, single-phase, dc-ac inverter. Assume all components to be ideal (i.e., zero power loss everywhere for the sake of simplicity).

The output of the boost dc-dc converter, operating in a continuous-current-conduction mode at a switching frequency of 250 kHz, is 250 V (dc) across a very large dc-link capacitor such that the ripple in the capacitor voltage can be assumed to be negligible. This capacitor voltage acts as the input to a single-phase, full-bridge, inverter that supplies power to the grid at a unity power factor; assume the ripple in the output current to be negligible. Inverter switches are sine-PWM controlled with the switching frequency of 100 kHz. Assume the inductance on the ac-side of the inverter to be negligible.

- (a) Draw the circuit diagram of such an interface and label all the components.
- (b) What is the duty-ratio of the transistor-switch in the boost dc-dc converter?
- (c) In the single-phase inverter, over one switching time-period, plot the duty-ratios, each below the other, of all the four transistor-switches as functions of time when the grid voltage is at its positive peak. Label your plots with appropriate numerical values.
- (d) What is the peak value of the current into the residential grid?

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Problem 9 (b) A synchronous machine is connected to an infinite bus as shown in the figure below. The machine has the following parameters: synchronous speed, $\omega_s = 120\pi \,[\text{rad/s}]$, inertia constant, $H = 8 \,[\text{s}]$, machine damping, $D = 0.004 \,[\text{rad}^{-1}\text{s}]$, machine terminal voltage, $E = 0.9 \,[\text{pu}]$, mechanical power input, $P_M = 1.0 \,[\text{pu}]$, machine terminal impedance, $X_M = 0.2 \,[\text{pu}]$, the infinite bus voltage magnitude, $v_{\infty} = 1.0 \,[\text{pu}]$, and the line impedance, $X_L = 0.25 \,[\text{pu}]$. Recall that the *swing equations* that govern the evolution of the rotor angle, δ , and frequency, ω , are given by:

$$\frac{d\delta}{dt} = \omega - \omega_{\rm s},$$

$$\frac{2H}{\omega_{\rm s}}\frac{d\omega}{dt} = P_M - P_E - D\left(\omega - \omega_{\rm s}\right),$$
(1)

where P_E is the electrical output power sourced by the generator from terminal 1.

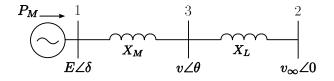


Figure 1: Single line diagram of single machine infinite bus

Solution 9 (b)

(i) Write an expression for the electrical output power, P_E. Your expression should only be a function of E, v_∞, δ, X_M, and X_L.
 Solution:

$$P_E = \frac{Ev_{\infty}}{X_M + X_L} \sin \delta \tag{2}$$

(ii) Find the equilibrium points for the system in (1) in the interval, [0, π].
 Solution:

Swing equations are given by:

$$\frac{2H}{\omega_s} \frac{\mathrm{d}^2 \delta}{\mathrm{d}t^2} + D \frac{\mathrm{d}\delta}{\mathrm{d}t} = P_M - P_E,$$

$$\rightarrow \quad 0.0424 \frac{\mathrm{d}^2 \delta}{\mathrm{d}t^2} + 0.004 \frac{\mathrm{d}\delta}{\mathrm{d}t} = 1 - 2\sin\delta$$

$$1 - 2\sin\bar{\delta} = 0$$

$$\rightarrow \quad \bar{\delta} = \frac{\pi}{6}, \frac{5\pi}{6}$$

(iii) Linearizing the system around the equilibrium point, find the eigenvalues. Solution:

$$x_1 = \delta, \quad x_2 = \frac{\mathrm{d}\delta}{\mathrm{d}t}$$

Then,

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ \frac{1}{0.0424} \left(1 - 2\sin x_1 - 0.004x_2 \right) \end{bmatrix}$$

Linearization around the equilibrium point, \bar{x}_1 , is:

$$\begin{bmatrix} \dot{x}_1\\ \dot{x}_2 \end{bmatrix} \simeq \begin{bmatrix} 0 & 1\\ -\frac{2}{0.0424}\cos x_1 & -0.004 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}$$

Linearization around the equilibrium points, $\bar{x}_1 := \bar{\delta} = \frac{\pi}{6}$, yields:

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} \simeq \begin{bmatrix} 0 & 1 \\ -40.8503 & -0.0943 \end{bmatrix} \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \end{bmatrix}$$

Linearization around the equilibrium points, $\bar{x}_1 := \bar{\delta} = \frac{5\pi}{6}$, yields:

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} \simeq \begin{bmatrix} 0 & 1 \\ 40.8503 & -0.0943 \end{bmatrix} \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \end{bmatrix}$$

(iv) Mention which equilibrium point is stable.

Solution:

Eigenvalues for the equilibrium point, $\bar{x}_1 := \bar{\delta} = \frac{\pi}{6}$, are $\lambda_{1,2} = -0.0471 \pm j6.3913$, which is stable. Eigenvalues for the equilibrium point, $\bar{x}_1 := \bar{\delta} = \frac{5\pi}{6}$, are $\lambda_{1,2} = 6.3444, -6.4387$, which is unstable.